

Getting Started with MicroPython on the Raspberry Pi Pico

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What, another one?

- Not a Linux machine: a microcontroller
- Custom silicon, designed by Raspberry Pi Foundation
- Lots of I/O
- Great documentation
- \$5.25 CAD, any qty
- Arduino killer





RP2040 Overview

- Dual-core ARM Cortex-M0+ at 133 MHz
- 264 KB RAM
- No Flash storage (Pico has 2 MB external)
- 26 × multi-function GPIO pins
- 2 × SPI, 2 × I2C, 2 × UART, 3
 × 12-bit ADC, 16 × PWM
- 8 × PIO state machines

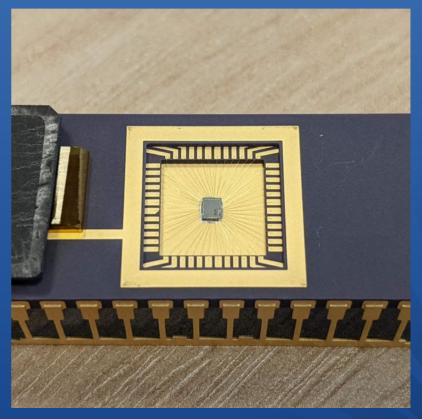


Image credit: Raspberry Pi Foundation

So where do I get one?

- In theory, you can buy as many as you want, but:
 - BuyaPi: Sold Out
 - Canakit: Sold Out(preorders ship Feb 28)
 - Elmwood: Sold Out
 - Newark, Digikey: on order

- My Canada Post experience
- BuyaPi: ordered Jan 21, arrived Feb 2.

 Average speed: house spider
- Elmwood: ordered Jan 27, arrived Feb 3.
 Average speed: 3-toed sloth
- Don't use Canada Post because

What is MicroPython?

- Python 3 implementation
- Small: 256 KB flash, 16 KB RAM [minimum]
- Compiled on-chip; standalone
- Subset of standard Python library
- Core developers were hired to implement for Pico
- Now includes ARMv6M assembler micropython.org



MicroPython Differences

- System libraries are typically limited, e.g.:
 - Strings are always UTF-8; 8-bit codecs excluded
 - Time is monotonic (fractional) seconds: no timezones or DST
 - No CSV, numpy, pip (→ upip), ...
- .py → .mpy [like .pyc] compilation isn't automatic
- Hardware interface modules:
 - machine: for hardware features like pins, PWM, I2C, ADC, ...
 - rp2: RP2040 PIO assembler, raw Flash access
- help() docstrings short or absent: see online docs

Flashing MicroPython

- Pico firmware is distributed as UF2 images
- Hold BOOTSEL while plugging in
- Pico appears as a USB storage device
- Drag/copy UF2 to PICO storage
- Pico reboots; USB disappears

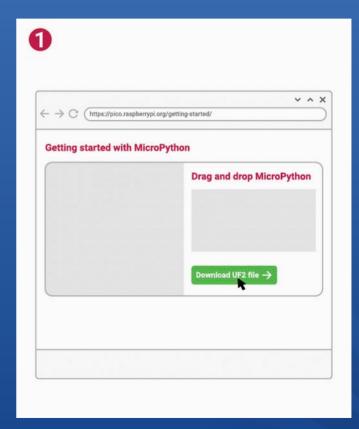


Image credit: Raspberry Pi Foundation

Editing: Thonny

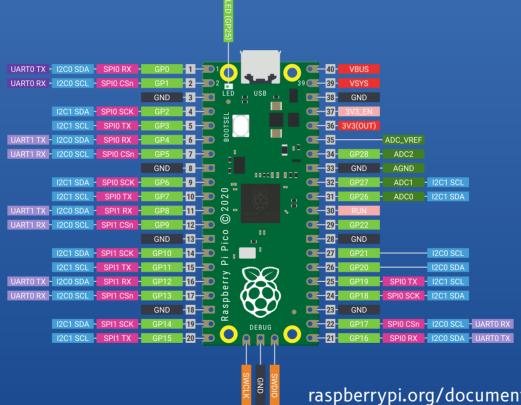
- Raspberry Pi Foundation's recommended editor
- Installed by default
- Includes loading/saving to Pico flash
- Has a simple graph tool
- ... plus firmware updater
- ... and (Raspberry) REPL sorry not sorry

```
- Raspberry Pi Pico :: /main.py @ 9:12
[ main.pv ]
     from math import sin, radians
     from time import sleep
     dx = 12
     while True:
         print["%6.3f %6.3f %6.3f %6.3f %6.3f" %
                [-1.2, \sin[radians[x]], \sin[radians[x + 120]],
                 sin[radians[x + 240]], 1.2]]
         x = [x + dx] \% 360
         sleep(0.1)
spberry Pi Pico with RP2040
     "help[]" for more information.
```

"but my \$EDITOR ...!!1!"

- You don't have to use Thonny
- ... it's just more work if you don't.
- The command-line MicroPython tool with REPL access is rshell:
 - https://github.com/dhylands/rshell/tree/pico
- Make sure you get the this branch, as it handles the quirks of the Pico's RTC
- ... and yes, the Foundation has shipped yet another device which doesn't have battery backup on its clock ®

All of the Pins



GPIO, PIO, and PWM 50 ADC SPI 12C System Control Debugging

raspberrypi.org/documentation/pico/getting-started

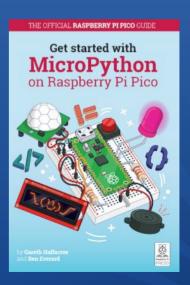
Documentation

- This is absolutely *stellar* for a board at launch + 3 weeks
- Data sheets, API guides, code, Fritzing parts ... all at raspberrypi.org/documentation/pico/getting-started









Unexpected Quirks

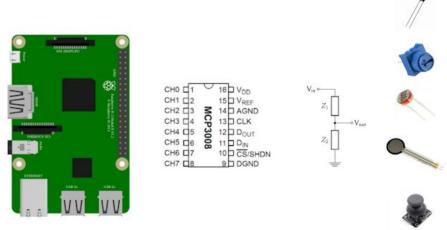
It's a new board, and folks are just learning, but:

- ADC: default analogue-to-digital setup is quite noisy
- 2 PWM: duty cycle changes if frequency is changed
- JUART Serial: has no wait/timeout, will lock if read and no data waiting
- 4 Dual core/threading: seems to be not well understood yet

Worked example

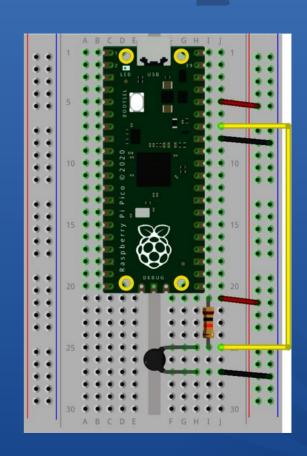
• Trevor Woerner used an MCP3008 with a thermistor and Raspberry Pi last month:

- Let's use a Pico
- ... which is cheaper than an MCP3008 [by 50¢!]
- ... and can act as a serial datalogger, perhaps writing to a Raspberry Pi over USB serial.



Wiring

- Pins used:
 - ADC2 (pin 34)
 - 3V3 (pin 36)
 - AGND (pin 33)
- 10 $k\Omega$ resistor between 3V3 and thermistor
- 10 k Ω @ 25 °C thermistor, β = 3977



Code!

```
from machine import Pin, ADC
from time import sleep
from math import log
led = Pin(25, Pin.OUT)
adc = ADC[2]
r25 = 10000
beta = 3977
while True:
  r = 10000.0 / (65535 / float[adc.read u16[]] - 1]
  lnr = log(r / r25)
  ts C = -273.15 + 1/[1/298.15 + lnr/beta]
   print['%5.1f' % [ts_C]]
   led.toggle()
```

sleep[2]